

# Poisson's equation for Markov chains

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# Outline

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# Discrete-time Markov chains

Let  $\Phi = \{\Phi_n, n \geq 0\}$  be a **time-homogeneous** discrete-time Markov chain (DTMC), evolving on a complete separable metric space  $E$ , whose Borel  $\sigma$ -algebra shall be denoted by  $\mathcal{B}(E)$ .

The transition kernel is denoted by  $P = (P(x, dy) : x, y \in E)$ . Suppose that  $P$  is  $\Psi$ -irreducible and Harris positive recurrent with the unique stationary distribution  $\pi = (\pi(dx) : x \in E)$ .

# Poisson's equation for DTMCs

Poisson's equation has the following form:

$$(I - P)\tilde{g} = \bar{g},$$

where  $I$  is the identity operator,  $\bar{g}(x) = g(x) - \pi(g)$ .

The function  $g$  is called **the forcing function** and is assumed to satisfy  $\pi(|g|) < \infty$ . The function  $\tilde{g}$  is called **a solution of Poisson's equation**.

# Uniqueness and existence

By Glynn & Meyn (1996), we know:

**Uniqueness:** If  $\tilde{g}_1$  and  $\tilde{g}_2$  are two solutions of Poisson's equation with  $\pi(|\tilde{g}_1| + |\tilde{g}_2|) < \infty$ , then  $\tilde{g}_1(x) = c + \tilde{g}_2(x)$  for some  $c$ .

**Existence:** A commonly used solution is given by

$$\tilde{g}_\alpha(x) = \mathbb{E}_x \left[ \sum_{k=0}^{\tau_\alpha - 1} \bar{g}(\Phi_k) \right], \quad x \in E,$$

where  $\alpha$  is an atom in  $\mathcal{B}(E)$ , and  $\tau_\alpha = \inf\{k \geq 1 : \Phi_k \in \alpha\}$ .



# Connection-CLT

Under some conditions, a central limit theorem (CLT) holds (Meyn & Tweedie 2009), i.e.

$$n^{-\frac{1}{2}} \sum_{k=1}^n \bar{g}(\Phi_k) \Rightarrow N(0, \sigma^2(\mathbf{g})), \quad \text{as } n \rightarrow \infty,$$

and the variance constant  $\sigma^2(\mathbf{g})$  is given by

$$\sigma^2(\mathbf{g}) = 2\mathbb{E}_\pi[\tilde{g}(\Phi_0)\bar{g}(\Phi_0)] - \mathbb{E}_\pi[\bar{g}^2(\Phi_0)].$$

# Connection-Hoeffding's inequality

▷ Hoeffding's inequality (Glynn & Ormoneit 2002, Choi & Li 2019, L. & Liu 2020):

If Poisson's equation admits a solution  $\tilde{g}$  such that  $\|\tilde{g}\|_\infty < \infty$ , then for any  $\varepsilon > 0$  and  $n > 2\|\tilde{g}\|_\infty/\varepsilon$ ,

$$\mathbb{P}_x \left( \frac{1}{n} \sum_{k=1}^n g(\Phi_k) - \pi(g) \geq \varepsilon \right) \leq \exp \left\{ \frac{-(n\varepsilon - 2\|\tilde{g}\|_\infty)^2}{2n\|\tilde{g}\|_\infty^2} \right\}.$$

# Connection-perturbation analysis

- ▷ Perturbation theory (Glynn & Meyn 1996, L. 2015):  
Let  $P$  and  $\tilde{P}$  be positive recurrent Markov chains with invariant probability distributions  $\pi$  and  $\nu$  respectively.

$$(\nu - \pi)g = \nu\Delta\tilde{g},$$

where  $\Delta = \tilde{P} - P$  is the perturbation.

- ▷ Truncation approximations to invariant distribution (Masuyama 2016, L. & Li 2018):

$$({}_{(n)}\pi - \pi)g = {}_{(n)}\pi\Delta\tilde{g}.$$

# Further connections of Poisson's equation

- ▶ Markov decision theory: Poisson's equation is known as the dynamic programming equation, and the functions  $g$  and  $\tilde{g}$  are called the cost function and the value function (Guo & Hernández-Lerma 2009).
- ▶ MCMC algorithms: variance reduction problems (Mijatović & Vogrinc 2019).
- ▶ Ergodicity for single-birth process with specific  $g$  (Chen & Zhang 2014).

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# Concern problems

**Solve the Poisson equation:** *QBD* processes: Dendievel, L. & Latouche(2013); Bini et al. (2016) (**General solution**); Liu L. & Zhao (2023) (matrix-analytical method for countable chains).

**Derive bounds on the solution:** Glynn & Meyn (1996); Wu (2009).

**Approximate the solution:** Mijatović & Vogrinc (2019); Liu, L. & Zhao (2022) (Augmented truncation).

▷ In this talk, we present **bounds and monotonicity** about a solution of Poisson's equation.

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# Petite set

Recall that a set  $C \in \mathcal{B}(E)$  is called a petite set if there exists a positive constant  $\lambda$ , probability distributions  $\varphi$  and  $a = (a(n), n \in \mathbb{Z}_+)$  such that

$$\sum_{n=0}^{\infty} a(n)P^n(x, \cdot) \geq \lambda\varphi(\cdot), \quad x \in C.$$

▷  $C$  is called a  $\nu_m$ -small set if  $a(n) = 1_{\{n=m\}}$ .

# Lyapunov drift condition

Drift condition for  $f$ -ergodicity:

$D(V,f,b,C)$ : There exists a positive constant  $b < \infty$ , a set  $C$  and finite functions  $V \geq 1$  and  $f \geq 1$  such that

$$PV(x) \leq V(x) - f(x) + b \cdot \mathbf{1}_C(x), \quad x \in E,$$

where  $\mathbf{1}_C(\cdot)$  is the indicator function in the set  $C$ .

- ▷ If  $f = \beta V$  for some  $0 < \beta < 1$ , then it responds to geometric ergodicity.
- ▷ If  $f = V^\alpha$  for some  $0 < \alpha < 1$ , then it responds to polynomial ergodicity.



# $f$ -ergodicity Drift condition

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# Bounds on a solution

## Theorem 1.(Glynn, Lin & L. 2023)

Suppose that  $D(V,f,b,C)$  holds for a petite set  $C$ . Then for any measurable function  $g$  satisfying  $0 \leq g \leq f$ , there exists a solution  $\tilde{g}$  such that

$$\frac{-b}{\inf_{x \in E} f(x)} (V(x) + bd) \leq \tilde{g}(x) \leq V(x) + bd, \quad \text{for } x \in E,$$

where  $d = \frac{1}{\lambda} \sum_{n=0}^{\infty} na(n)$ .

Remark: 1) If  $C$  be an atom, then  $d = 1$ ;

2) If  $C$  is a  $\nu_m$ -small set, then  $d = \frac{m}{\nu_m(E)}$ .

# Comparison with Meyn & Glynn (1996)

Under the same condition, Meyn & Glynn (1996) established the following upper bound

$$|\tilde{g}(x)| \leq c[V(x) + 1]$$

for some implicit constant  $c$ . Our bound presents an explicit representation of the constant  $c$

$$|\tilde{g}(x)| \leq \max \left\{ \frac{b}{\inf_{x \in E} f(x)}, 1 \right\} [V(x) + bd].$$

# Key ideas in proof

- ▶ Construct a split chain and obtain the solution of Poisson equation

$$\tilde{g}(x) = \mathbb{E}_x \left[ \sum_{j=0}^{\tau-1} \bar{g}(X_j) \right].$$

- ▶ Apply the comparison theorem and properties of the split chain to bound  $\tilde{g}(x)$ .
- ▶ A detailed analysis of the bounds on  $\mathbb{E}_x \left[ \sum_{j=0}^{\tau-1} l_C(X_j) \right]$ .

# Application: truncation approximation

Let  $V$  be a coercive function such that a sublevel set  $A_n := \{x : V(x) \leq n\}$  is either empty or compact. Let  $N(C) = \min\{n : C \subseteq A_n\}$  for a set  $C$ .

**Corollary 1** Suppose that there exists a petite set  $C$  such that  $\{(n)P, n \geq N(C)\}$  uniformly satisfies  $D(V, f, b, C)$ . Then we have

$$\|\pi - (n)\pi\|_f \leq b[n + d(b+1)]\pi(A_n^c) + \int_{y \in A_n^c} \pi(dy)V(y).$$

Moreover, if  $\pi(V) < \infty$ , then  $\|\pi - (n)\pi\|_f \rightarrow 0$  as  $n \rightarrow \infty$ .

# Application: asymptotic variance

**Corollary 2** Suppose that  $D(V, f, b, C)$  holds for a petite set  $C$  and that  $\pi(V^2) < \infty$ . Then for any measurable function  $g$  with  $0 \leq g \leq f$ , we have

$$\begin{aligned}\gamma_g^2 &:= \lim_{n \rightarrow \infty} \frac{1}{n} \mathbb{E}_\pi[(S_n(\bar{g}))^2] \\ &= 2\mathbb{E}_\pi[\tilde{g}(\Phi_0)\bar{g}(\Phi_0)] - \mathbb{E}_\pi[\bar{g}^2(\Phi_0)] \\ &\leq 2\text{Cov}_\pi(V(\Phi_0), g(\Phi_0)) - \mathbb{E}_\pi[\bar{g}^2(\Phi_0)].\end{aligned}$$

If  $\gamma_g^2 > 0$ , then a CLT holds.

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# Stochastically ordered Markov Chains

Let  $\Phi_n$  be a DTMC on the state space  $E = \mathbb{R}^+$  or  $E = \mathbb{Z}^+$ .

Let  $\Phi_n^1$  and  $\Phi_n^2$  be two copies of  $\Phi_n$  with different initial states and the same transition kernel.

The chain  $\{\Phi_k, k \geq 0\}$  is called stochastically ordered if  $\Phi_n^1$  is stochastically larger than  $\Phi_n^2$  ( $P(\Phi_n^1 \leq z) \leq P(\Phi_n^2 \leq z)$ ,  $z \in E$ ) for any  $n \geq 1$ , whenever  $\Phi_0^1$  is stochastically larger than  $\Phi_0^2$ .



# Monotonicity for a solution

Suppose that the state 0 is accessible, then

$$\tilde{g}_0(x) = \mathbb{E}_x \left[ \sum_{k=0}^{\tau_0-1} \bar{g}(\Phi_k) \right], \quad x \in E,$$

is a solution of Poisson's equation.

## Theorem 2 (Liu & L. 2023)

Let  $\Phi_n$  be a Harris positive recurrent and stochastically ordered Markov chain with invariant distribution  $\pi$ . If the state 0 is accessible from any other state,  $g(x)$  is non-decreasing in  $x$  and  $\pi(|g|) < \infty$ , then  $\tilde{g}_0(x)$  is also non-decreasing.

# Key ideas in proof

- ▶ Stochastic ordering is distributionally equivalent to pathwise ordering in the sense that

$$\Phi_n^1(\omega^1) \geq \Phi_n^2(\omega^2) \text{ if } \Phi_0^1(\omega^1) \geq \Phi_0^2(\omega^2).$$

- ▶ Note  $\bar{g}(x) = g(x) - \pi(g)$  is non-decreasing in  $x$ .
- ▶ For  $x \geq y$

$$\tilde{g}_0(x) = \mathbb{E}_x \left[ \sum_{k=0}^{\tau_0^1-1} \bar{g}(\Phi_k^1) \right] \geq \mathbb{E}_y \left[ \sum_{k=0}^{\tau_0^2-1} \bar{g}(\Phi_k^2) \right] = \tilde{g}_0(y).$$

# Comparison

## Comparison with Glynn & Infanger (2022):

- (1) For  $E = \mathbb{Z}^+$ , both results are the same. For  $E = \mathbb{R}^+$ , the results differ in the assumptions.
- (2) Different arguments.

# Block-Structured Markov Chains

Let  $\{(X_k, Y_k), k \geq 0\}$  be a block-structured two-dimensional Markov chain with a countable state space  $E = \bigcup_{i=0}^{\infty} \ell(i)$ , where

$$\ell(i) := \{(i, j), i \geq 0, 1 \leq j \leq d\}$$

denotes the level set. These chains are useful for modelling the phase-type queues. (Neuts 1988, Latouche and Ramaswami 1998.)

Let  $\mathbf{P} = (P(k, i; l, j))_{(k,i),(l,j) \in E}$  be the transition probability matrix of the chain  $\{(X_k, Y_k), k \geq 0\}$ .

# Block-Monotone Markov chains (BMMC)

A stochastic matrix  $\mathbf{P}$  is called stochastically block-monotone with block size  $d \geq 1$  if for all  $k, \ell \geq 0$ ,

$$\sum_{m=\ell}^{\infty} P(k, i; m, j) \leq \sum_{m=\ell}^{\infty} P(k+1, i; m, j), \quad 1 \leq i, j \leq d.$$

A function  $\mathbf{g} = g(i, j)_{(i, j) \in E}$  is called block non-decreasing with block size  $d$  if for all  $i \geq 1$ ,  $1 \leq j \leq d$ , we have  $g(i, j) \leq g(i+1, j)$ .

For a fixed state  $(\alpha', \alpha'') \in E$ ,

$$\tilde{g}_{(\alpha', \alpha'')}(k, i) = \mathbb{E}_{(k, i)} \left[ \sum_{k=0}^{\tau_{(\alpha', \alpha'')} - 1} \bar{g}(X_k, Y_k) \right], \quad (k, i) \in E,$$

is one solution of Poisson's equation.

### Theorem 3 (Liu & L. 2023)

Suppose that  $\{(X_k, Y_k), k \geq 0\}$  is an irreducible and positive recurrent **BMMC**. If the forcing function  $g$  is **block non-decreasing** with size  $d$  and satisfies  $\pi(|g|) < \infty$ , then for any state  $(\alpha', \alpha'') \in E$ , the solution  $\tilde{g}_{(\alpha', \alpha'')}$  is also **block non-decreasing** with size  $d$ .

# Key ideas of proof

- ▶ Our arguments are based on the sample path analysis. We first consider the case of  $(\alpha', \alpha'') = (0, 1)$ .
- ▶ Masuyama (2015) shows that a block-monotone Markov Chain, is pathwise ordered in the first variable  $X_k$  given the same second phase variable.
- ▶ For the general case of  $(\alpha', \alpha'')$ , we know that

$$\tilde{\mathbf{g}}_{(\alpha', \alpha'')} - \tilde{\mathbf{g}}_{(0,0)} = \tilde{\mathbf{g}}_{(\alpha', \alpha'')}(0, 1)\mathbf{e}.$$

# An illustrative example

We consider a quasi-birth-and-death (QBD) process with transition matrix  $P$  given by

$$P = \begin{pmatrix} A_{-1} + A_0 & A_1 & 0 & 0 & \cdots \\ A_{-1} & A_0 & A_1 & 0 & \cdots \\ 0 & A_{-1} & A_0 & A_1 & \cdots \\ 0 & 0 & A_{-1} & A_0 & \cdots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}.$$

Obviously  $P$  is block-monotone.



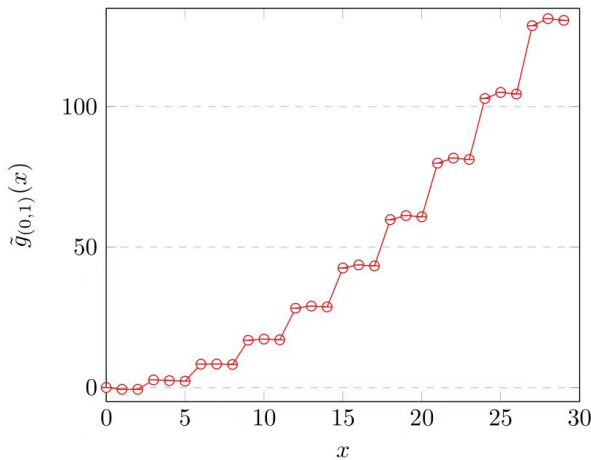
Here, we let

$$A_{-1} = \begin{pmatrix} 0.3 & 0.2 & 0.1 \\ 0.2 & 0 & 0.3 \\ 0.3 & 0 & 0.2 \end{pmatrix}, \quad A_0 = \begin{pmatrix} 0.1 & 0.1 & 0 \\ 0 & 0.2 & 0.1 \\ 0.2 & 0.1 & 0 \end{pmatrix},$$

and

$$A_1 = \begin{pmatrix} 0.1 & 0 & 0.1 \\ 0.1 & 0.1 & 0 \\ 0 & 0.1 & 0.1 \end{pmatrix}.$$

Now, take  $g(i, j) = i + \frac{1}{j+1}, i \geq 0, j \in \{1, 2, 3\}$ . Based on Liu, L. & Zhao (2023), we obtain  $\pi(|g|) \approx 1.2658 < \infty$  and the solution  $\tilde{g}_{(0,1)}$ .



**Figure:** The values of the solution  $\tilde{g}_{(0,1)}$

# Non-recurrent BMBCs

For a non-recurrent BMBC and a finite **non-negative** function  $g$ , Poisson's equation is written as

$$(I - P)\tilde{g} = g.$$

The function  $\tilde{g}_\infty$ , defined by

$$\tilde{g}_\infty(k, i) = \mathbb{E}_{(k, i)} \left[ \sum_{k=0}^{\infty} g(X_k, Y_k) \right], \quad (k, i) \in E,$$

is the minimal non-negative solution of Poisson's equation.

# Block monotonicity

## Theorem 4 (Liu & L. 2023)

Let  $\{(X_k, Y_k), k \geq 0\}$  be an irreducible and non-recurrent BMMC. If the forcing function  $g$  is block non-increasing with size  $d$ , then the solution  $\tilde{g}_\infty$  is also block non-increasing with size  $d$ .

**Remark 2.** In fact, if the forcing function  $g$  is block non-decreasing, the solution  $\tilde{g}_\infty$  is also block non-decreasing. However, in this case, the solution function  $\tilde{g}_\infty = \infty$ .

# Concluding remarks

- (1) The results for bound and monotonicity of the Poisson equation can be expected to **hold for continuous-time Markov processes**.
- (2) It is interesting to extend the concept of **block-monotonicity to Markov switching fluid queue/ Brownian motion**

Thank you for your attention!